Second-order Extension of Hooke's Law in Elasticity Based on a New Boltzmann-type Collision Model

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Development of hybrid DG code and computational simulation of rarefied & microscale gas flows

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Development of viscoelastic code and computational simulation of viscoelastic flows

Hooke's law in elasticity (1676)



In the physics and mechanics of elastic solids, Hooke's law is an empirical law that states that the force needed to extend or compress a spring is proportional linearly to the distance.

The law is named after 17thcentury British physicist Robert Hooke who first stated the law in 1676.

Hooke's law is only a first-order approximation to the real response of springs and other elastic bodies to applied forces.

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Elastic dumbbell models: kinetic theory of polymers

Hyper-elastic materials such as rubber (amorphous solid)



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Classification of gas flows in non-equilibrium



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Boltzmann kinetic equations

 A first-order partial differential equation of the probability density of finding a particle in phase space with an integral collision term

$$\left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla\right) f(t, \mathbf{r}, \mathbf{v}) = \frac{1}{Kn} C[f, f_2]$$

Movement Kinematic Collision (or Interaction) Dissipation

$$C[f, f_2] \sim \int |\mathbf{v} - \mathbf{v}_2| (f^* f_2^* - f f_2) d\mathbf{v}_2$$

= Gain (scattered into) - Loss (scattered out) = $\left(\frac{\partial f}{\partial t}\right)$ -

$$\left(\frac{\delta f}{\delta t}\right)^+ - \left(\frac{\delta f}{\delta t}\right)^+$$

• Maxwell's equation of transfer for molecular expression $h^{(n)}$

$$\frac{\partial}{\partial t} \left\langle h^{(n)} f \right\rangle + \nabla \cdot \left(\mathbf{u} \left\langle h^{(n)} f \right\rangle + \left\langle \mathbf{c} h^{(n)} f \right\rangle \right) - \left\langle f \frac{d}{dt} h^{(n)} \right\rangle - \left\langle f \mathbf{c} \cdot \nabla h^{(n)} \right\rangle = \left\langle h^{(n)} C[f, f_2] \right\rangle$$

Relationship with conservation laws (moments)

Boltzmann transport equation (BTE): 10²³

$$\left(\frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla\right) f(t, \mathbf{r}, \mathbf{v}) = C[f, f_2] \qquad \qquad p\mathbf{u} = \langle m\mathbf{v} f(t, \mathbf{r}, \mathbf{v}) \rangle$$
where $\langle \cdots \rangle = \iiint \cdots dv_x dv_y dv_z$

Differentiating the statistical definition $\rho \mathbf{u} \equiv \langle m \mathbf{v} f(t, \mathbf{r}, \mathbf{v}) \rangle$ with time and then combining with BKE $(t, \mathbf{r}, \mathbf{v})$ are independent and $\mathbf{v} = \mathbf{u} + \mathbf{c}$)

$$\frac{\partial}{\partial t} \langle m\mathbf{v}f \rangle = \left\langle m\mathbf{v} \frac{\partial f}{\partial t} \right\rangle = -\left\langle m(\mathbf{v} \cdot \nabla f) \mathbf{v} \right\rangle + \left\langle m\mathbf{v}C[f, f_2] \right\rangle$$

$$\begin{bmatrix} \mathbf{A} \end{bmatrix}^{(2)} : \text{ Traceless symmetric} \\ \text{ part of tensor } \mathbf{A} \\ \text{Here } -\left\langle m(\mathbf{v} \cdot \nabla f) \mathbf{v} \right\rangle = -\nabla \cdot \left\langle m\mathbf{v}\mathbf{v}f \right\rangle = -\nabla \cdot \left\{ \rho \mathbf{u}\mathbf{u} + \left\langle m\mathbf{c}\mathbf{c}f \right\rangle \right\}$$

After the decomposition of the stress into pressure and viscous shear stress

$$\mathbf{P} \equiv \langle m\mathbf{c}\mathbf{c}f \rangle = p\mathbf{I} + \mathbf{\Pi} \text{ where } p \equiv \langle m\mathrm{Tr}(\mathbf{c}\mathbf{c})f/3 \rangle, \ \mathbf{\Pi} \equiv \langle m[\mathbf{c}\mathbf{c}]^{(2)}f \rangle,$$

and using the collisional invariance of the momentum, $\langle m\mathbf{v}C[f, f_2] \rangle = 0$, we have

$$\frac{\partial(\rho \mathbf{u})}{\partial t} + \nabla \cdot \left(\rho \mathbf{u}\mathbf{u} + p\mathbf{I} + \mathbf{\Pi}\right) = \mathbf{0}$$

Conservation laws: 13

Closing-last balanced closure on open terms

$$\mathbf{\Pi} \equiv \left\langle m [\mathbf{c}\mathbf{c}]^{(2)} f \right\rangle, \mathbf{Q} \equiv \left\langle m c^2 \mathbf{c} / 2f \right\rangle$$

Closure theory: how, where (open terms), when (last)

New balanced closure with closure-last approach (PoF 2014)

2nd-order for kinematic LH = 2nd-order for collsion RH

$$\frac{D}{Dt} (\mathbf{\Pi} / \rho) + \nabla \cdot \Psi^{(\Pi)} + 2 [\mathbf{\Pi} \cdot \nabla \mathbf{u}]^{(2)} + 2 p [\nabla \mathbf{u}]^{(2)} = \left\langle m [\mathbf{cc}]^{(2)} C [f, f_2] \right\rangle$$

$$\overset{2^{\text{nd-order closure}}}{= -\frac{p}{\mu_{NS}}} \frac{1}{\mathbf{\Pi}} q_{2nd}(\kappa_1) \text{ where } \Psi^{(\Pi)} = \left\langle m \mathbf{ccc} f \right\rangle - \left\langle m \mathrm{Tr}(\mathbf{ccc}) f \right\rangle \mathbf{I} / 3$$

$$\frac{D}{Dt} \left(\Psi^{(\Pi)} / \rho \right) + \nabla \cdot \Xi + \dots = \left\langle h^{(\Psi^{(\Pi)})} C[f, f_2] \right\rangle$$

Other collision operator

Collision operator
$$C(f_{i}, f_{j})$$
Boltzmann
$$\int d\mathbf{u}_{j} \int_{0}^{\pi} d\phi \int_{0}^{\infty} db \ bg_{ij}(f_{i}^{*}f_{j}^{*} - f_{i}f_{j})$$
Vlasov-Landau
$$2\pi e_{i}^{2} e_{j}^{2} \ln \Lambda \int d\mathbf{u}' \partial_{ij} \cdot \mathbf{U}'(\mathbf{g}) \cdot \partial_{ij} f_{i}(\mathbf{u}') f_{j}(\mathbf{u}')$$
Balescu-Lenard
$$\sum_{\mathbf{k}} \frac{\pi \omega_{i}^{2} \omega_{j}^{2}}{n_{i}^{2} m_{i}} (\mathbf{k}/k^{2}) \cdot \partial_{u} \int d\mathbf{u}'(\mathbf{k}/k^{2}) \cdot (m_{j} \ \partial_{u} - m_{i} \partial_{u'}) f_{i}(\mathbf{u}) f_{j}(\mathbf{u}') \frac{\delta(\mathbf{k} \cdot \mathbf{u} - \mathbf{k} \cdot \mathbf{u}')}{|\epsilon(\mathbf{k}, \mathbf{k} \cdot \mathbf{u})|^{2}}$$
Fokker-Planck
$$-2\pi e_{i}^{2} e_{j}^{2} m_{i}^{-1} \ln \Lambda \ \partial_{u\alpha} \int d\mathbf{u}' [f_{i}(\mathbf{u}) \partial_{u'\beta} f_{j}(\mathbf{u}')/m_{j} - f_{j}(\mathbf{u}') \partial_{u\beta} f_{i}(\mathbf{u})] U_{\alpha\beta}(\mathbf{u} - \mathbf{u}')$$

$$U'_{\alpha\beta}(\mathbf{x}) = \mathbf{x}^{-3} (\mathbf{x}^{2} \delta_{\alpha\beta} - \mathbf{x}_{\alpha} \mathbf{x}_{\beta}); \quad \partial_{ij} = m_{i}^{-1} \partial_{u} - m_{j}^{-1} \partial_{u'}; \quad \mathbf{g} = \mathbf{u} - \mathbf{u}';$$

$$\omega_{i}^{2} = 4\pi n_{i} e_{i}^{2}/m_{i}; \quad \ln \Lambda = \text{Coulomb logarithm};$$

$$\epsilon(\mathbf{k}, \omega) = 1 + \sum_{i} (\omega_{i}^{2}/k^{2}) \int d\mathbf{u}(\omega - \mathbf{k} \cdot \mathbf{u}) \mathbf{k} \cdot \partial_{u} f_{i}(\mathbf{u}).$$
If there are no external forces, and conditions are uniform throughout the gas, this equation takes the form (equation (16)):

Boltzmann

$$\frac{\partial f(x,t)}{\partial t} = \int_{0}^{\infty} \int_{0}^{x+x'} \left[\frac{f(\xi,t)}{\sqrt{\xi}} \frac{f(x+x'-\xi,t)}{\sqrt{(x+x'-\xi)}} - \frac{f(x,t)f(x't)}{\sqrt{x}} \right]_{\sqrt{x'}} \frac{f(x,t)f(x't)}{\sqrt{x'}}$$

where the variables x and x' denote the energies of two molecules before a collision, and ξ and $(x+x'-\xi)$ denote their energies after the collision; $\psi(x, x', \xi)$ is a function which depends on the nature of the forces between the molecules.

(1872)

Talk 8/23

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Closure of dissipation terms via 2nd-law

Key ideas; exponential canonical form, consideration of entropy production σ , and non-polynomial expansion called as cumulant expansion (B. C. Eu in 80-90s)

By writing the distribution function f in the exponential form

$$f = \exp\left[-\beta\left(\frac{1}{2}mc^2 + \sum_{n=1}^{\infty} X^{(n)}h^{(n)} - N\right)\right], \ \beta \equiv \frac{1}{k_B T}$$

Nonequilibrium entropy Ψ : $\Psi(\mathbf{r},t) = -k_B \langle \left[\ln f(\mathbf{v},\mathbf{r},t) - 1 \right] f(\mathbf{v},\mathbf{r},t) \rangle$,

Nonequilibrium entropy production: $\sigma_c = -k_B \langle \ln f \ C[f, f_2] \rangle \ge 0$ (satisfying 2nd-law)

 $\sigma_c = \kappa_1 q(\kappa_1^{(\pm)}, \kappa_2^{(\pm)}, \cdots)$ via cumulant expansion

$$\sigma_{c} \equiv -k_{B} \left\langle \ln f \ C[f, f_{2}] \right\rangle = \frac{1}{T} \sum_{n=1}^{\infty} X^{(n)} \left\langle h^{(n)} C[f, f_{2}] \right\rangle = \frac{1}{T} \sum_{l=1}^{\infty} X^{(n)} \Lambda^{(n)},$$

a thermodynamically-consistent constitutive equation, still exact to BKE, can be derived;

$$\rho \frac{D(\mathbf{\Pi} / \rho)}{Dt} + \nabla \cdot \mathbf{\Psi}^{(\Pi)} + 2 \left[\mathbf{\Pi} \cdot \nabla \mathbf{u} \right]^{(2)} + 2 p \left[\nabla \mathbf{u} \right]^{(2)} = \frac{1}{\beta g} \sum_{l=1}^{\infty} \mathbf{R}_{12}^{(2l)} X_2^{(l)} q(\mathbf{\kappa}_1^{(\pm)}, \mathbf{\kappa}_2^{(\pm)}, \cdots)$$

Note: When f is truncated to a finite number of terms, the set is truncated in such a way that the divergence problem would not arise.

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Cumulant expansion method

$$\left\langle x^{l} \right\rangle = \int x^{l} f(x) dx, \quad \left\langle e^{\lambda x} \right\rangle = \int e^{\lambda x} f(x) dx$$
Then we have
$$\left\langle e^{\lambda x} \right\rangle = \sum_{l=0}^{\infty} \frac{\lambda^{l}}{l!} \left\langle x^{l} \right\rangle = \exp\left[\sum_{l=1}^{\infty} \frac{\lambda^{l}}{l!} \kappa_{l}\right] \text{ where }$$

$$\kappa_{l} = \left[\frac{d^{l}}{d\lambda^{l}} \ln\left\langle e^{\lambda x} \right\rangle\right]_{\lambda=0}; \quad \kappa_{1} = \left\langle x \right\rangle, \quad \kappa_{2} = \left\langle x^{2} \right\rangle - \left\langle x \right\rangle^{2}, \cdots \text{ (mean, variance)}$$

$$\left\langle e^{x} \right\rangle_{\text{polynomical}} = 1 + \left\langle x \right\rangle + \frac{1}{2!} \left\langle x^{2} \right\rangle + \frac{1}{3!} \left\langle x^{3} \right\rangle + \cdots,$$

$$\left\langle e^{x} \right\rangle_{\text{cumulant}} = \exp^{\left[\left\langle x \right\rangle + \frac{1}{2!} \left(\left\langle x^{2} \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle x \right\rangle - \left\langle x \right\rangle^{2}\right) + \cdots \right]} \left[\exp^{\left(\left\langle$$

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2nd-order NCCR model

Sinh{1st-order theory}

Navier-Fourier laws inclusive _____ like onion!

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Topology of 2nd-order NCCR (shock structure) (PoF 2020)



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Topology of 2nd-order NCCR (velocity shear) (PoF 2016)



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3D mixed modal DG method for the 2nd-order model

$$\partial_{t} \mathbf{U} + \nabla \mathbf{F}_{inv} (\mathbf{U}) + \nabla \mathbf{F}_{vis} (\mathbf{U}, \nabla \mathbf{U}) = 0$$

Discretization in mixed form
$$\begin{cases} \mathbf{S} - \nabla \mathbf{U} = \mathbf{0} \\ \partial_{t} \mathbf{U} + \nabla \mathbf{F}_{inv} (\mathbf{U}) + \nabla \mathbf{F}_{vis} (\mathbf{U}, \mathbf{S}) = 0 \end{cases}$$

JCP 2022
NSF model $(\mathbf{\Pi}, \mathbf{Q}) = \mathbf{f}_{linear} (\mathbf{S}(\mathbf{U}))$
NCCR model $(\mathbf{\Pi}, \mathbf{Q})_{NCCR} = \mathbf{f}_{non-linear} (\mathbf{S}(\mathbf{U}), p, T) \end{cases}$
NCCR: Nonlinear Coupled
Constitutive Relation
$$\mathbf{U}_{h}(\mathbf{x}, t) = \sum_{i=0}^{k} U_{j}^{i}(t) \varphi^{i}(\mathbf{x}), \quad \mathbf{S}_{h}(\mathbf{x}, t) = \sum_{i=0}^{k} S_{j}^{i}(t) \varphi^{i}(\mathbf{x})$$

$$\begin{cases} \frac{\partial}{\partial t} \int_{I} \mathbf{U} \varphi dV - \int_{I} \nabla \varphi \mathbf{F}_{inv} dV + \int_{\partial I} \varphi \mathbf{F}_{inv} \cdot \mathbf{n} d\Gamma - \int_{I} \nabla \varphi \mathbf{F}_{vis} dV + \int_{\partial I} \varphi \mathbf{F}_{vis} \cdot \mathbf{n} d\Gamma = 0, \\ \int_{I} \mathbf{S} \varphi dV + \int_{I} T^{s} \nabla \varphi \mathbf{U} dV - \int_{\partial I} T^{s} \varphi \mathbf{U} \cdot \mathbf{n} d\Gamma = 0, \end{cases}$$

Dubiner basis function, Lax-Friedrichs inviscid flux, central flux for viscous terms

2-D hypersonic rarefied flow past a cylinder



Argon gas Mach 5.48 Knudsen 0.02

Argon gas Mach 5.48 Knudsen 0.2

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New nonlinear intramolecular interaction model



$$\frac{\partial}{\partial t} \int_{R} \boldsymbol{U} d\boldsymbol{V} = \text{In} - \text{Out} = \oint_{S} \boldsymbol{F} \cdot (-\boldsymbol{n}) dS$$

Conservation in control volume

New nonlinear intramolecular interaction model for the "spring" in the dumbbell

When linearized, it reduces to $(f^{eq} - f) / \lambda$ (BGK model, 1954)

Preprint (2023): A Boltzmann-type kinetic intramolecular model and its application to viscoelastic fluids

Boltzmann-type intramolecular interaction model

A molecular-level equation of the marginal probability density function of finding a dumbbell in the configuration vector space **r** connecting two beads for a given time, $f(\mathbf{r}, t)(\varsigma$ friction coefficient, **s** spring force, $\lambda \equiv \varsigma / 4S_0$ relaxation)

$$\frac{\partial f}{\partial t} + \nabla \cdot \left((\nabla \mathbf{u})^T \mathbf{r} - \frac{2k_B T}{\varsigma} \nabla \right) f = \nabla \cdot \left(\frac{2\mathbf{s}}{\varsigma} f \right)$$
 Fokker-Planck
 $\mathbf{s} = S_0 \mathbf{r}$: Linear Hookean

$$\frac{\partial f}{\partial t} + \nabla \cdot \left((\nabla \mathbf{u})^T \mathbf{r} - \frac{2k_B T}{\varsigma} \nabla \right) f = \frac{1}{2\lambda} \left(f^* - f \right)$$
 New Boltzmann-type

Note that the interaction occurs through the "spring" in the dumbbell. For the dumbbell models the forces on the two beads are equal and opposite, leading to a connector force.

Corresponding second-order constitutive model

Nonequilibrium entropy Ψ : $\Psi(\mathbf{r},t) = -k_B \langle \left[\ln f(\mathbf{v},\mathbf{r},t) - 1 \right] f(\mathbf{v},\mathbf{r},t) \rangle$,

Nonequilibrium entropy production:

$$\sigma_{c} \equiv -k_{B} \left\langle \ln f \ C[f] \right\rangle = \frac{1}{4\lambda} k_{B} \left\langle \ln \left(f^{*}/f \right) \left(f^{*}-f \right) \right\rangle \geq 0 \text{ (satisfying 2nd-law)}$$

since $\ln \left(x/y \right) (x-y) \geq 0$.
$$\sigma_{c} = \frac{1}{4\lambda} k_{B} \left\langle f^{(0)} \left(x-y \right) [\exp(-y) - \exp(-x)] \right\rangle = \kappa_{1} q(\kappa_{1}^{(\pm)}, \kappa_{2}^{(\pm)}, \cdots) \text{ via cumulant expansion}$$

$$\sigma_{c} \equiv -k_{B} \left\langle \ln f \ C[f] \right\rangle = \frac{1}{T} \sum_{n=1}^{\infty} X^{(n)} \left\langle h^{(n)} C[f] \right\rangle = \frac{1}{T} \sum_{l=1}^{\infty} X^{(n)} \Lambda^{(n)},$$

a thermodynamically-consistent constitutive equation can be derived;

$$\frac{D\mathbf{\tau}}{Dt} - \left[(\nabla \mathbf{u})^T \mathbf{\tau} + \mathbf{\tau} \nabla \mathbf{u} \right] - \frac{\mu}{\lambda} (\nabla \mathbf{u}^T + \nabla \mathbf{u}) = -\frac{1}{\lambda} \mathbf{\tau} q_{2nd}(\kappa_1),$$
$$q_{2nd}(\kappa_1) = \frac{\sinh \kappa_1}{\kappa_1}, \ \kappa_1 = \alpha \frac{\sqrt{\mathbf{\tau} : \mathbf{\tau}}}{\mu/\lambda} \ (\mathbf{\tau} \equiv nS_0 \langle \mathbf{rr} f \rangle - nk_B T \mathbf{I})$$

2nd-order extension of Hooke's Law in elasticity



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Application to viscoelastic fluids



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Computational simulation of viscoelastic fluids



Implementation of the new model to viscoelastic OpenFOAM (cylinder flow)

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Viscoelastic fluids: Barus effect in die swell





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Concluding remarks

Proposal of a new Boltzmann-type kinetic spring model

$$\frac{1}{2\lambda} \left(f^* - f \right) \qquad \text{Cf. } \frac{1}{\lambda} \left(f^{(0)} - f \right)$$

BGK (1954) Yamamoto (1956), Lodge

(1964), Modified network model

Second-order extension of Hooke's law in elasticity

 $\hat{\tau} = \frac{\sinh^{-1}(\alpha \hat{\tau}_0)}{\alpha}$

Application to viscoelastic fluids

Similarities between rarefied gases and viscoelastic fluids